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EAST UKRAINIAN NATIONAL UNIVERSITY  
Department "Logistics management  
and traffic safety in transport»

PJSC «UKRZALIZNYTSIA»  
Regional branch «Donetsk railway»

MANAGEMENT UKRTRANSBEZPEKA  
IN LUHANSKAYA REGION

**GLOBALIZATION OF SCIENTIFIC  
AND EDUCATIONAL SPACE.  
INNOVATIONS OF TRANSPORT.  
PROBLEMS, EXPERIENCE, PROSPECTS**

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<b>Tartakovsky E., Gorobchenko A., Antonovych A.</b> THE EVALUATION OF THE "DRIVER-LOCOMOTIVE" ERGATIC SYSTEM PERFORMANCE QUALITY .....	187
<b>Tartakovsky E., Sumtsov A., Artemenko O., Bragin N.</b> CONDITION AND TRENDS RENEWAL OF DIESEL LOCOMOTIVES IN UKRAINE .....	190
<b>Tkachenko S.</b> USE OF GENETIC ALGORITHMS FOR SOLVING THE PROBLEM OF OPTIMIZATION OF INTERCITY FREIGHT TRAFFIC USING ROAD TRANSPORT .....	193
<b>Troyan A., Muzykin M.</b> ENERGY EFFICIENCY MANAGEMENT OF TRAIN TRAFFIC VOLUME AS A MEANS OF IMPROVING TRANSPORTATION PROCESS .....	195
<b>Turpak S., Vasilyeva L., Lebid H., Padchenko O., Sidorenko Yu.</b> OPTIMIZATION OF THE RAILWAY TRANSPORTATION SCHEDULE OF METALLURGICAL ENTERPRISE .....	197
<b>Fomin A., Braykovska N., Nechyporuk A., Kovalchuk G., Fomin V.</b> ECONOMIC EVALUATION OF USING UPGRADED HOPPER CARS FOR TRANSPORTATION OF HOT PELLETS AND AGGLOMERATE OF 20-9749 MODEL .....	199
<b>Fomin O., Logvinenko O., Burlutskyi O.</b> SYNOPSIS OF THE THERMAL METHOD FOR STRAIGHTENING TECHNOLOGICAL-DEFORMED CAR PARTS .....	201
<b>Fomin A., Stetsko A.</b> THE STRUCTURING POSSIBILITIES OF RESISTANCE OF USE TANTINIUM LOAD WAYS THE OPPOSITE OF THE STRESS AND/OR STRAIN STATE OF WAGON DESIGNS .....	204
<b>Kharlamov P., Kharlamova E.</b> ROLLING STOCK MAINTENANCE SCHEDULING OPTIMIZATION .....	206

- distribution the information leaflets, which contain information about dangerous road sections of the region, among drivers at the gas stations;

- development the Internet site named "Interactive map of emergency hazardous road sections in Zaporizhzhya region". This site will contain information with warning to drivers about the location of dangerous road sections of the region;

- to make a proposal to GPS map designers to include into maps information about dangerous road sections on the vehicle route along with the names and location of streets, road intersections etc.

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## THE EVALUATION OF THE "DRIVER-LOCOMOTIVE" ERGATIC SYSTEM PERFORMANCE QUALITY

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According to the statistics [1], the proportion of the safe railway operation violations in the locomotive facilities is 31% of the total amount of the Ukrzaliznytsya. And on analyzing dangerous situations causes the human factor is 27%. These indicators prove that there is a significant reserve for improving safety of operation by minimizing human beings' harmful impact on operating.

The criterion of the "driver-locomotive" ergatic system performance quality in control can be represented as the correlation between various quality indicators reflecting different properties of the system.

Complex criterion of the system quality defined in the form of:

$$K = \sum_{i=1}^n \gamma_i I_i, \quad (1)$$

where  $\gamma_i$  is the weight coefficient of the  $i$  indicator  $I_i$ ,  $i \in [1, n]$ ;

$n$  – number of partial criteria.

Each of the partial criteria is functionality

$$I_i = I_i(x, u, x_{36}, x_{ny}, x_{kc}, q_{n\sigma}, t) = I_i(\bar{X}), \quad (2)$$

where  $x$  is the vector of the locomotive technical state;

$u$  is the control vector;

$xse$  is the specifying effects vector;

$xic$  is the initial conditions vector.

$xf_s$  is the vector of final state;

$qlc$  is the locomotive crews work quality;

$t$  is the time during which system is investigated.

The factors of utility given in the work [2, 3] are used as criteria. Parameters that characterize the utility of a decision taken by the system are the values of the emergency situation complexity, deviations from the schedule and power consumption for traction.

The utility of decision is defined in the three-dimensional coordinate system  $(Xec; G; \Delta t)$ , where  $Xec$  is the emergency situation complexity,  $G$  is the energy consumption for the movement of trains,  $\Delta t$  is the deviation from the schedule. The utility of the action in this case will be determined by the length of the vector, deferred from the origin of coordinates to the point  $(Xec; G; \Delta t)$ , which is determined by the forecasted value of the specified values in the result of a decision made by the system [4].

Thus the expression (1) can be substantiated and presented in the form of

$$K = \sum_{i=1}^3 \gamma_i I_i \quad (3)$$

where  $I_1$  is partial criterion of safe railway operation;  $I_2$  is partial criterion of energy consumption for haulage of train;  $I_3$  is partial criterion for the on-time train performance;  $\gamma_i$  is weight coefficient of  $i$ -th partial criterion.

When operating locomotive decision making depends on many circumstances. It is proposed to determine the basic train control strategy that can be applied in various situations.

Control strategy is introduced as the set containing its characteristic parameters  $S_l \in (\pi_1, \pi_2, \dots, \pi_j)$ , where  $\pi_j$  is the  $j$ -th indicator of the implementation of the strategy  $s_l$ . There are functions  $\pi_j = f(I_i)$  that determine the impact of each criterion on the performance of this control strategy. The influence of the value of a control quality criterion on the indicator  $\pi_j$  characterizing each particular strategy is evaluated by comparing deriva-

tives  $\frac{d\pi_j}{dI_i}$ . And the total impact of criterion  $I_i$  on the strategy  $s_l$  is taken as the arithmetic mean of the derivatives

$$A_{I_i/s_l} = \frac{\sum_{j=1}^{k_{s_l}} \frac{d\pi_j}{dI_i}}{k_{s_l}} \quad (4)$$

where  $A_{I_i/s_l}$  is the magnitude of the  $I_i$  criterion influence on the  $s_l$  control strategy;

$k_{s_l}$  is the number of  $s_l$  strategy indicators.

So the absolute indicators of influence of each control quality criterion on the implementation of the particular control strategies are received.

To obtain the values of the weight coefficients when calculating control quality with different strategies it is necessary to use a well-known transition from absolute indicators to relative ones:

$$\gamma_i(s_l) = \frac{A_{I_i/s_l}}{\sum_{i=1}^n A_{I_i/s_l}}, \quad (5)$$

where  $\gamma_i(s_l)$  is the weight coefficient of the  $i$ -th criterion for the  $l$ -th strategy.

$A_{I_i/s_l}$  is the magnitude of the  $I_i$  criterion influence on the  $s_l$  control strategy;

$\sum_{i=1}^n A_{I_i/s_l}$  is the summary absolute value of all control quality  $n$  criteria influence on the implementation of the  $l$ -th strategy.

Thus, using different strategies the formal indicator of the train control quality has been obtained.

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